Gantry Path Planning

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Education

National Tsing Hua University

September 2019 - April 2022

Master of Science

Department of Power Mechanical Engineering

Master Thesis: A Research of Watering Gantry Robot in Greenhouse

- Convolution Neural Network (YOLOv4)
- Object Pose Estimation Robot Operation System (ROS)

National Tsing Hua University

September 2015 - June 2019

January 2020

Bachelor of Science

Department of Power Mechanical Engineering (GPA: 3.86/4.3)

Courses:

- Control System
- Artificial Intelligence Electronics
- Evolutionary Computation

Experience

MediaTek Inc. March 2022 - Now

R&D ASIC Engineer

HIWIN Technologies Corp. July 2017 - August 2017

Summer practical training

Skills

o C/C++ Python ROS Linux/Shell script

Certificates

Japanese-Language Proficiency Test

N1 Level

TOEIC September 2016

Score of 765

Projects

Robot Arm Control January 2018

- o This is a course project of "Program design for mechatronic control system"
- \circ Using C/C++ to control and plan the motion of the wafer robot by using NC code.
- Get the only A+ grade in the course.

June 2021 **Chat Bot**

- o A side project that design a chat bot on Plurk using python.
- Using Oauth1 authentication to communicate between client and server.
- Learn to increase the web server robustness and error handling.